

Pointwise estimates of solutions to nonlinear equations for nonlocal operators

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Abstract. We study pointwise behavior of positive solutions to nonlinear integral equations, and related inequalities, of the type

$$u(x) - \int_{\Omega} G(x, y) g(u(y)) d\sigma(y) = h,$$

where (Ω, σ) is a locally compact measure space, $G(x, y): \Omega \times \Omega \rightarrow [0, +\infty]$ is a kernel that satisfies a weak form of the maximum principle, $h \geq 0$ is a measurable function, and $g: [0, \infty) \rightarrow [0, \infty)$ is a monotone increasing function.

In the special case where G is Green's function of the Laplacian (or fractional Laplacian) that satisfies the maximum principle and $h = 1$, a typical global pointwise bound for any supersolution $u > 0$ is given by

$$u(x) \geq F^{-1}(G\sigma(x)), \quad x \in \Omega,$$

where $F(t) := \int_1^t \frac{ds}{g(s)}, t \geq 1$, and necessarily

$$G\sigma(x) < F(\infty) = \int_1^{+\infty} \frac{ds}{g(s)},$$

for every $x \in \Omega$ such that $u(x) < \infty$.

This problem is motivated by the semilinear fractional Laplace equation

$$(-\Delta)^{\frac{\alpha}{2}} u - g(u)\sigma = \mu \quad \text{in } \Omega, \quad u = 0 \quad \text{in } \Omega^c,$$

with measure coefficients σ, μ , where $g(u) = u^q, q > 0$, and $0 < \alpha < n$, in domains $\Omega \subseteq \mathbb{R}^n$, or Riemannian manifolds, with positive Green's function G .

In a similar way, we treat positive solutions to the equation

$$u(x) + \int_{\Omega} G(x, y) g(u(y)) d\sigma(y) = h,$$

and the corresponding fractional Laplace equation $(-\Delta)^{\frac{\alpha}{2}} u + g(u)\sigma = \mu$, with a monotone decreasing function g , in particular $g(u) = u^q, q < 0$.

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1. Introduction

We study pointwise behavior of non-negative solutions u to nonlinear integral equations (and related inequalities) of the type

$$u(x) = \int_{\Omega} G(x, y) g(u(y)) d\sigma(y) + h(x), \quad x \in \Omega. \quad (1.1)$$

Here Ω is a locally compact Hausdorff space, σ is a Radon measure on Ω , $G(x, y): \Omega \times \Omega \rightarrow [0, +\infty]$ is a lower semicontinuous function, $g: [0, \infty) \rightarrow [0, \infty)$ is a monotone increasing continuous function, and $h \geq 0$ is a given σ -measurable function.

We also treat positive solutions to more general equations and inequalities with measure-valued kernels G , or equivalently, operator equations of the type

$$u = T(g(u)) + h \quad \text{in } \Omega \quad (1.2)$$

on a measurable space (Ω, Ξ) , where T is a positivity preserving linear operator acting in the cone of measurable functions $\Omega \rightarrow [0, +\infty]$, and continuous with respect to pointwise limits of monotone increasing sequences of functions (see Section 2, Examples 2.2-2.4).

Our main applications are to positive weak solutions of the semilinear fractional Laplace problem with measure coefficients,

$$(-\Delta)^{\frac{\alpha}{2}} u - u^q \sigma = \mu \quad \text{in } \Omega, \quad u = 0 \text{ in } \Omega^c, \quad (1.3)$$

where $q > 0$, $0 < \alpha < n$, and μ, σ are Radon measures in a domain $\Omega \subseteq \mathbb{R}^n$ (or a Riemannian manifold) with positive Green's function G . Equation (1.3) is equivalent to the integral equation (1.1) with

$$h = G\mu = \int_{\Omega} G(\cdot, y) d\mu(y).$$

Similar results are obtained for the integral equation

$$u(x) = - \int_{\Omega} G(x, y) g(u(y)) d\sigma(y) + h(x), \quad x \in \Omega, \quad (1.4)$$

where g is a monotone decreasing function, and the corresponding fractional Laplace problem

$$(-\Delta)^{\frac{\alpha}{2}} u + u^q \sigma = \mu \quad \text{in } \Omega, \quad u = 0 \text{ in } \Omega^c, \quad (1.5)$$

in the case $q < 0$.

More precisely, we obtain sharp global lower bounds for non-negative measurable functions u satisfying the integral inequality

$$u(x) \geq G(g(u) d\sigma)(x) + h(x) \quad \text{in } \Omega \quad (1.6)$$

in the case of monotone increasing g , and upper bounds for solutions of

$$u(x) \leq -G(g(u) d\sigma)(x) + h(x) \quad \text{in } \Omega \quad (1.7)$$

in the case of monotone decreasing g .

We assume that the kernel G satisfies the following form of the *weak maximum principle*:

For any Radon measure ν in Ω with compact support $K = \text{supp}(\nu)$,

$$G\nu \leq 1 \text{ in } K \implies G\nu \leq \mathfrak{b} \text{ in } \Omega, \quad (1.8)$$

with some constant $\mathfrak{b} \geq 1$.

This property of G is sometimes referred to as the generalized, or rough maximum principle (see [1, 17, 19]), and is known for many local and non-local operators. It is used extensively in this paper, together with a weak form of the domination principle (1.11) considered below.

These basic principles make it possible to extend the results of [13], where classical solutions to (1.3) and (1.5), with continuous σ, μ (not necessarily positive), were treated for the (weighted) Laplace operator on Euclidean domains and weighted Riemannian manifolds, to certain nonlocal problems for integral operators with kernel G , and measures σ, μ . The exact value of the constant \mathfrak{b} in (1.8) is not essential, although it appears in various constants in our estimates, which are sharp if $\mathfrak{b} = 1$ (in particular, in the case of local operators).

As suggested by the referee, we list some examples of operators L whose associated kernel G satisfies (1.8). Notice that not all of these examples are independent, and some of them contain others as special cases. Related examples and various extensions can be found in [2, 7, 8, 11, 19].

- (1) The Laplace operator $L = -\Delta$ on a domain $\Omega \subseteq \mathbb{R}^n$ ($n \geq 1$) which has a nontrivial positive Green's function G (see [13, 19]);
- (2) The Laplace-Beltrami operator $L = -\Delta$ on a Riemannian manifold M_n which has a nontrivial positive Green's function G , and more generally its weighted analogue $L = -\frac{1}{\omega} \text{div}(\omega \nabla)$ on a weighted Riemannian manifold (see [12, 13]);
- (3) The fractional Laplace or Laplace-Beltrami operator $L = (-\Delta)^{\frac{\alpha}{2}}$ ($0 < \alpha \leq 2$) on a domain $\Omega \subseteq \mathbb{R}^n$, or a Riemannian manifold M_n , respectively, which has a nontrivial positive Green's function G ([2, 19]);
- (4) The fractional Laplace operator $L = (-\Delta)^{\frac{\alpha}{2}}$ ($0 < \alpha < n$), or $L = (1 - \Delta)^{\frac{\alpha}{2}}$ ($\alpha > 0$) on \mathbb{R}^n , or a ball, or half-space ([1, 8]);
- (5) Convolution operators $Lf = k \star f$ on \mathbb{R}^n with radial monotone non-increasing kernel $k : \bar{\mathbb{R}}^+ \rightarrow \bar{\mathbb{R}}^+$ discussed below after Theorem 1.1 (see also [1, Theorem 2.6.2]);
- (6) Integral operators with quasi-metric kernels $G : \Omega \times \Omega \rightarrow (0, +\infty]$ on a locally compact Hausdorff space Ω such that $d(x, y) = \frac{1}{G(x, y)}$ satisfies the quasi-triangle inequality with constant \varkappa (see Section 4 below, and also [8, 15, 16]);
- (7) Second-order differential operators $L = -\text{div}(a \nabla \cdot) - b \cdot \nabla + c$ in divergence form, with real-valued measurable coefficients $a = (a_{ij})$, $b = (b_i)$ and c , where b and $c \geq 0$ are bounded, and a is symmetric and uniformly elliptic, with Green's function G on an open subset $\Omega \subseteq \mathbb{R}^n$ ([2, 11]);

- (8) Second-order differential operators with real-valued continuous coefficients in non-divergence form $L = -\sum_{i,j} a_{ij} \partial_i \partial_j - b \cdot \nabla + c$, where $c \geq 0$, and a is symmetric and positive definite, with Green's function G on an open subset $\Omega \subseteq \mathbb{R}^n$ ([2, 11]);
- (9) More generally, Green's functions G associated with connected Brelot spaces ([2, 7, 11]);
- (10) More generally, \mathfrak{B} -harmonic Bauer spaces with Green's function G ; in particular, the heat kernel associated with the operator $\frac{\partial}{\partial t} + L$, where L is either one of the operators in Example 7 or 8 ([2, 7, 11]).

We remark that in Examples 1-3 and 7-10 we have $\mathfrak{b} = 1$ in (1.8). In Examples 4 and 5, the constant \mathfrak{b} depends on n , whereas in Example 6 we have $\mathfrak{b} \leq 8\pi^3$ (see Lemma 4.2 below).

There are well-known cases where Green's function G of the operator L is known explicitly, for instance, $G(x, y) = \min(x, y)$ for $Lu = -u''$ on the positive half-axis \mathbb{R}^+ with zero boundary condition $u(0) = 0$, or $G(x, y) = c_{\alpha, n} |x - y|^{\alpha-n}$ for $L = (-\Delta)^{\frac{\alpha}{2}}$ ($0 < \alpha < n$) on \mathbb{R}^n . For bounded $C^{1,1}$ -domains $\Omega \subset \mathbb{R}^n$, there are explicit two-sided estimates of Green's function of $L = (-\Delta)^{\frac{\alpha}{2}}$ ($0 < \alpha \leq 2$, $\alpha < n$):

$$G(x, y) \approx \left[\frac{\delta(x) \delta(y)}{|x - y|^2 + \delta(x) \delta(y)} \right]^{\frac{\alpha}{2}} |x - y|^{\alpha-n}, \quad x, y \in \Omega,$$

where $\delta(x) = \text{dist}(x, \partial\Omega)$. These estimates can be used in combination with our results to provide more explicit pointwise estimates of solutions (see, for instance, [8, 14]). Examples providing explicit estimates of Green's functions for $L = -\Delta$ on Riemannian manifolds can be found in [11].

In the case $h = 1$ our main result is the following theorem.

Theorem 1.1. *Let G satisfy in Ω the weak maximum principle (1.8) with constant $\mathfrak{b} \geq 1$. Assume that g is a monotone non-decreasing positive continuous function in $[1, +\infty]$, and set*

$$F(t) = \int_1^t \frac{ds}{g(s)}, \quad t \geq 1.$$

If u is a positive measurable function on Ω that satisfies

$$u(x) \geq G(g(u) d\sigma)(x) + 1 \tag{1.9}$$

for σ -almost all $x \in \Omega$, then, at any point $x \in \Omega$ where (1.9) is satisfied and $u(x) < +\infty$, we have

$$G\sigma(x) < \mathfrak{b} F(\infty) = \mathfrak{b} \int_1^{+\infty} \frac{ds}{g(s)},$$

and

$$u(x) \geq 1 + \mathfrak{b} \left[F^{-1}(\mathfrak{b}^{-1} G\sigma(x)) - 1 \right].$$

For a similar result in a more general setup of measure-valued kernels (Example 2.2), see Theorem 3.2; non-increasing nonlinearities g are treated in Theorem 3.3.

For example, for $g(s) = s^q$ with $q > 0, q \neq 1$, we obtain

$$u(x) \geq 1 + \mathfrak{b} \left[\left(1 + \frac{(1-q)G\sigma(x)}{\mathfrak{b}} \right)^{\frac{1}{1-q}} - 1 \right],$$

where in the case $q > 1$ necessarily

$$G\sigma(x) < \frac{\mathfrak{b}}{q-1}.$$

In the case $q = 1$ we have

$$u(x) \geq 1 + \mathfrak{b} \left(e^{\mathfrak{b}^{-1}G\sigma(x)} - 1 \right).$$

Theorem 1.1 and its corollaries yield global pointwise estimates for positive solutions to a broad class of elliptic and parabolic PDE, as well as non-local problems on Euclidean domains and manifolds. In particular, they are applicable to convolution equations on \mathbb{R}^n of the type

$$u = k \star (g(u)d\sigma) + 1. \quad (1.10)$$

Here

$$k \star (fd\sigma)(x) = \int_{\mathbb{R}^n} k(x-y)f(y)d\sigma(y),$$

where $k = k(|x|) > 0$ is an arbitrary lower semi-continuous, radially non-increasing function on \mathbb{R}^n . Such kernels are known to satisfy the weak maximum principle (1.8) with constant \mathfrak{b} which depends only on the dimension n of the underlying space (see [1, Theorem 2.6.2]).

To treat more general right-hand sides $h \geq 0$, we invoke a weak form of the *domination principle* for kernels G with respect to a Radon measure σ on Ω and a lower semi-continuous function h :

For any bounded measurable function $f \geq 0$ with compact support,

$$G(fd\sigma)(x) \leq h(x) \text{ in } \text{supp}(f) \implies G(fd\sigma)(x) \leq \mathfrak{b} h(x) \text{ in } \Omega, \quad (1.11)$$

provided $G(fd\sigma)$ is bounded on $\text{supp}(f)$.

Closely related properties are sometimes referred to as the dilated domination principle, the complete maximum principle, or the second maximum principle in the case $\mathfrak{b} = 1$ (see [2, 18, 19], and Sections 4 and 5 below).

We observe that the weak domination principle holds for Green's kernels associated with a large class of elliptic and parabolic problems, along with many non-local operators, and certain classes of functions h . In particular, (1.11) holds with $\mathfrak{b} = 1$ for nonnegative superharmonic functions h in Examples 1-3 and 7-9

considered above, but generally fails in Example 10 (some additional assumptions are needed). It is still true for $L = \frac{\partial}{\partial t} - \Delta$ and the classical heat kernel G with $h = G\nu + c$ for nonnegative measures ν and constants c ; see [2, 7].

Our main estimates in the case of general h and $g(t) = t^q$, $q \in \mathbb{R} \setminus \{0\}$, are contained in the following theorem. A more general statement in the context of measure-valued kernels G can be found in Theorem 5.1 below.

Theorem 1.2. *Let $h > 0$ be a lower semi-continuous function in Ω . Let G be a non-negative kernel in $\Omega \times \Omega$ which satisfies the domination principle (1.11) with respect to h with constant $\mathfrak{b} \geq 1$. Suppose that u is a non-negative function such that $u^q \in L^1_{\text{loc}}(\sigma)$, which satisfies (1.6) if $q > 0$, and (1.7) if $q < 0$. Then if $q > 0$ ($q \neq 1$), we have*

$$u(x) \geq h(x) \left\{ 1 + \mathfrak{b} \left[\left(1 + \frac{(1-q) G(h^q d\sigma)(x)}{\mathfrak{b} h(x)} \right)^{\frac{1}{1-q}} - 1 \right] \right\}, \quad x \in \Omega, \quad (1.12)$$

where in the case $q > 1$ necessarily

$$G(h^q d\sigma)(x) < \frac{\mathfrak{b}}{q-1} h(x), \quad (1.13)$$

for all $x \in \Omega$ such that $0 \leq u(x) < +\infty$, and (1.6) holds.

In the case $q = 1$,

$$u(x) \geq h(x) \left[1 + \mathfrak{b} \left(e^{\mathfrak{b}^{-1} \frac{G(hd\sigma)(x)}{h(x)}} - 1 \right) \right], \quad x \in \Omega. \quad (1.14)$$

If $q < 0$, then

$$u(x) \leq h(x) \left\{ 1 - \mathfrak{b} \left[1 - \left(1 - \frac{(1-q) G(h^q d\sigma)(x)}{\mathfrak{b} h(x)} \right)^{\frac{1}{1-q}} \right] \right\}, \quad x \in \Omega, \quad (1.15)$$

and necessarily

$$G(h^q d\sigma)(x) < \frac{\mathfrak{b}}{1-q} \left[1 - (1 - \mathfrak{b}^{-1})^{1-q} \right] h(x), \quad (1.16)$$

for all $x \in \Omega$ such that $u(x) > 0$, $h(x) < +\infty$, and (1.7) holds.

These estimates with $h = G\mu$ yield the corresponding lower bounds for positive weak solutions $u \in L^q_{\text{loc}}(\sigma)$ to the inequality

$$(-\Delta)^{\frac{\alpha}{2}} u - u^q \sigma \geq \mu \quad \text{in } \Omega, \quad u = 0 \text{ in } \Omega^c,$$

for $q > 0$, and the upper bounds for positive weak solutions to the inequality

$$(-\Delta)^{\frac{\alpha}{2}} u + u^q \sigma \leq \mu \quad \text{in } \Omega, \quad u = 0 \text{ in } \Omega^c,$$

for $q < 0$, where μ, σ are Radon measures in an arbitrary domain $\Omega \subseteq \mathbb{R}^n$ with positive Green's function G in the case $0 < \alpha \leq 2$, when the domination principle holds with $\mathfrak{b} = 1$. They also hold in the case $0 < \alpha < n$ (with some constant $\mathfrak{b} \geq 1$) provided Green's function G is quasi-metric, or quasi-metrically modifiable, for instance, if Ω is the entire space, a ball, or half-space (see [8]).

For classical solutions and local elliptic differential operators, such estimates were obtained earlier in [13] in the case where $\sigma \in C(\Omega)$ is a continuous function which may change sign, and $\mu \geq 0$ is a locally Hölder continuous function in $\Omega \subseteq \mathbb{R}^n$, or a smooth Riemannian manifold.

In the linear case $q = 1$, estimate (1.14) in Theorem 1.2 obviously yields

$$u(x) \geq h(x) e^{\mathfrak{b}^{-1} \frac{G(hd\sigma)(x)}{h(x)}}, \quad x \in \Omega.$$

This is a refinement (with sharp constant in the case $\mathfrak{b} = 1$) of the lower bound obtained in [8] along with a matching upper bound, for quasi-metric kernels G . See Sections 4 and 5 where these and more general classes of kernels are treated.

In the superlinear case $q > 1$, the necessary condition (1.13) was found in [16] for quasi-metric kernels G (without the explicit constant), and in [3] for the Laplace operator $-\Delta$ with Dirichlet boundary conditions, with sharp constant $\frac{1}{q-1}$. In the latter case, the domination principle holds with $\mathfrak{b} = 1$, so that this constant is the same as in (1.13).

There are certain upper bounds for u in the case $q > 1$, and lower bounds in the case $q < 0$, which are true for general non-negative kernels G (without the weak domination principle) provided conditions (1.13) and (1.16) respectively hold with smaller constants depending on q , which ensure the existence of positive solutions ([13, Theorem 3.5]; see also [3, 12, 16] for $q > 1$).

For the *homogeneous* problem (1.6) with $h = 0$ in the sublinear case $0 < q < 1$, we have a similar lower estimate for non-trivial solutions u (see Corollary 3.6 for a more general setup of measure-valued kernels). No such estimates of positive solutions to (1.6) or (1.7) with $h = 0$ are available for $q \geq 1$ or $q < 0$, respectively.

Theorem 1.3. *Let $0 < q < 1$. Suppose G is a non-negative kernel on $\Omega \times \Omega$ satisfying the weak maximum principle (1.8) with constant $\mathfrak{b} \geq 1$. If $u \in L_{\text{loc}}^q(\sigma)$, $u > 0$, is a solution to the integral inequality (1.6) with $h = 0$, that is, $u \geq G(u^q d\sigma)$ in Ω , then*

$$u(x) \geq (1 - q)^{\frac{1}{1-q}} \mathfrak{b}^{-\frac{q}{1-q}} [G\sigma(x)]^{\frac{1}{1-q}}, \quad x \in \Omega. \quad (1.17)$$

If $\mathfrak{b} = 1$, then the constant $(1 - q)^{\frac{1}{1-q}}$ in (1.17) is the same as in the local case ([13, Theorem 3.3]), and is sharp. This estimate was first deduced in [4] for solutions to the equation $-\Delta u = u^q \sigma$ on \mathbb{R}^n (without the sharp constant). See also [5, 6] for matching lower and upper bounds of solutions to the equation $(-\Delta)^{\frac{\alpha}{2}} u = u^q \sigma$ ($0 < \alpha < n$) on \mathbb{R}^n in the case $0 < q < 1$.

We remark that necessary and sufficient conditions for the existence of a positive solution in the case $0 < q < 1$ to the homogeneous equation $u = G(u^q d\sigma)$

in Ω for quasi-symmetric kernels G which satisfy the weak maximum principle are given in [22] (see also [21]).

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2. The weak maximum principle and iterated estimates

We first prove a series of lemmas.

Lemma 2.1. *Let (Ω, ω) be a σ -finite measure space, and let $a = \omega(\Omega) \leq +\infty$. Let $f: \Omega \rightarrow [0, +\infty]$ be a measurable function. Let $\phi: [0, a) \rightarrow [0, +\infty)$ be a continuous, monotone non-decreasing function, and set $\phi(a) := \lim_{t \rightarrow a^-} \phi(t) \in (0, +\infty]$. Then the following inequality holds:*

$$\int_0^{\omega(\Omega)} \phi(t) dt \leq \int_{\Omega} \phi(\omega(\{z \in \Omega: f(z) \leq f(y)\})) d\omega(y). \quad (2.1)$$

Proof. If $\omega(\Omega) = \infty$ then consider an exhausting sequence $\{\Omega_k\}_{k=1}^{\infty}$ of measurable subsets of Ω with $\omega(\Omega_k) < +\infty$. Since

$$\begin{aligned} & \int_{\Omega} \phi(\omega(\{z \in \Omega: f(z) \leq f(y)\})) d\omega(y) \\ & \geq \int_{\Omega_k} \phi(\omega(\{z \in \Omega_k: f(z) \leq f(y)\})) d\omega(y), \end{aligned}$$

it suffices to prove (2.1) for Ω_k instead of Ω and then let $k \rightarrow \infty$. Hence, we can assume without loss of generality that $a = \omega(\Omega) < \infty$.

If ϕ is unbounded (as $t \rightarrow a^-$) then replace ϕ by a bounded function $\phi_j = \min(\phi, j)$, prove (2.1) for ϕ_j and then let $j \rightarrow \infty$. Therefore, we assume in what follows that ϕ is continuous on $[0, a]$.

Assume first that the function f is simple, that is, f takes on only a finite set of values $\{b_i\}_{i=1}^N$ where the sequence $\{b_i\}$ is arranged in the increasing order. Set

$$a_i = \omega\{z \in \Omega: f(z) \leq b_i\} \text{ for } i = 1, \dots, N$$

and $a_0 = 0$. If $y \in \Omega$ is such that $f(y) = b_i$, then

$$\phi(\omega\{z \in \Omega: f(z) \leq f(y)\}) = \phi(a_i).$$

It follows that

$$\begin{aligned}
 & \int_{\Omega} \phi(\omega\{z \in \Omega: f(z) \leq f(y)\}) d\omega(y) \\
 &= \sum_{i=1}^N \int_{\{y \in \Omega: f(y)=b_i\}} \phi(\omega\{z \in \Omega: f(z) \leq f(y)\}) d\omega(y) \\
 &= \sum_{i=1}^N \phi(a_i) \omega\{y \in \Omega: f(y) = b_i\} \\
 &= \sum_{i=1}^N \phi(a_i) (a_i - a_{i-1}).
 \end{aligned}$$

Since the function ϕ is non-decreasing, we obtain

$$\sum_{i=1}^N \phi(a_i) (a_i - a_{i-1}) \geq \sum_{i=1}^N \int_{a_{i-1}}^{a_i} \phi(t) dt = \int_{a_0}^{a_N} \phi(t) dt = \int_0^{\omega(\Omega)} \phi(t) dt,$$

whence (2.1) follows.

Let f be an arbitrary measurable function. By a standard argument, there is an increasing sequence $\{f_n\}$ of simple functions such that $f_n \uparrow f$ as $n \rightarrow \infty$. Applying the first part of the proof to f_n , we obtain

$$\begin{aligned}
 \int_{\Omega} \phi(\omega\{z \in \Omega: f_n(z) \leq f(y)\}) d\omega(y) &\geq \int_{\Omega} \phi(\omega\{z \in \Omega: f_n(z) \leq f_n(y)\}) d\omega(y) \\
 &\geq \int_0^{\omega(\Omega)} \phi(t) dt.
 \end{aligned}$$

The sequence $F_n(y) := \omega\{z \in \Omega: f_n(z) \leq f(y)\}$ of functions of $y \in \Omega$ is decreasing in n and converges to $\omega\{z \in \Omega: f(z) \leq f(y)\}$ as $n \rightarrow \infty$. Since ϕ is bounded and continuous and $\omega(\Omega) < \infty$, we obtain by the bounded convergence theorem that

$$\begin{aligned}
 & \lim_{n \rightarrow \infty} \int_{\Omega} \phi(\omega\{z \in \Omega: f_n(z) \leq f(y)\}) d\omega(y) \\
 &= \int_{\Omega} \phi(\omega\{z \in \Omega: f(z) \leq f(y)\}) d\omega(y),
 \end{aligned}$$

whence (2.1) follows. \square

In the rest of the section we assume that (Ω, \mathfrak{E}) is a measurable space, and that $G(x, dy)$ is a σ -finite kernel in Ω , which means that, for any $x \in \Omega$, $G(x, dy)$ is a σ -finite measure on (Ω, \mathfrak{E}) , and this measure depends on x measurably. The latter means that, for any \mathfrak{E} -measurable function $f: \Omega \rightarrow [0, \infty]$, the function

$$Gf(x) = \int_{\Omega} f(y) G(x, dy)$$

is also Ξ -measurable. We assume here that G satisfies the *weak maximum principle* in the following form:

There is a constant $\mathfrak{b} \geq 1$ such that, for any non-negative bounded measurable function f on Ω ,

$$Gf \leq 1 \text{ in } \{f > 0\} \implies Gf \leq \mathfrak{b} \text{ in } \Omega. \quad (2.2)$$

Clearly, (2.2) implies the following: for any $\varepsilon \geq 0$,

$$Gf \leq \varepsilon \text{ in } \{f > 0\} \implies Gf \leq \varepsilon \mathfrak{b} \text{ in } \Omega. \quad (2.3)$$

Let us consider some examples where this framework is applicable.

Example 2.2. Let Ω be a locally compact Hausdorff space with countable base. Assume that $G(x, dy)$ is a *Radon kernel* in Ω , that is, for any $x \in \Omega$, $G(x, dy)$ is a Radon measure on Ω (in particular, σ -finite). The weak maximum principle for a Radon kernel G can be stated as follows:

For any bounded measurable function f with compact support,

$$Gf \leq 1 \text{ in } \text{supp}(f) \implies Gf \leq \mathfrak{b} \text{ in } \Omega. \quad (2.4)$$

Then the weak maximum principle holds also in the form (2.2) by approximating an arbitrary function f by $f1_F$ with compact F .

Example 2.3. Let Ω again be a locally compact Hausdorff space with countable base, and let ω be a Radon measure on Ω . Suppose $K : \Omega \times \Omega \rightarrow [0, +\infty]$ is a measurable function such that $K(x, \cdot) \in L^1_{\text{loc}}(\Omega, \omega)$ for any $x \in \Omega$. Then set

$$G(x, E) := \int_E K(x, y) d\omega(y), \quad (2.5)$$

so that G is a Radon kernel in the above sense. In this case we have

$$Gf(x) = \int_{\Omega} K(x, y) f(y) d\omega(y).$$

Example 2.4. Let (Ω, Ξ) be a measurable space. Let T be a positivity preserving linear operator acting in the cone of measurable functions $\Omega \rightarrow [0, +\infty]$. Assume also that T is continuous with respect to pointwise limits of monotone increasing sequences of functions.

Fix some $x \in \Omega$ and define the measure

$$\omega_x(E) = T1_E(x), \quad E \in \Xi.$$

Then, for any non-negative measurable function f on Ω , we have

$$Tf(x) = \int_{\Omega} f d\omega_x. \quad (2.6)$$

Indeed, if u is a simple function of the form

$$f = \sum_{i=1}^{\infty} f_i 1_{E_i},$$

where f_i are non-negative constants, then

$$Tf(x) = \sum_{i=1}^{\infty} f_i T1_{E_i}(x) = \sum_{i=1}^{\infty} u_i \omega_x(E_i) = \int_{\Omega} f d\omega_x.$$

For a general measurable function f one proves (2.6) by passing to the limit using an increasing sequence of simple functions.

The measure ω_x is clearly σ -additive. The σ -finiteness of ω_x has to be assumed in addition (for example, if $T1(x) < \infty$ then the measure ω_x is finite). Assuming that ω_x is σ -finite, set $G(x, dy) := d\omega_x(y)$, or equivalently,

$$G(x, E) = \int_E G(x, dy) = T1_E(x), \quad E \in \Xi. \quad (2.7)$$

The following is the key lemma used repeatedly throughout this paper.

Lemma 2.5. *Let (Ω, Ξ) be a measurable space, and let $G(x, dy)$ be a σ -finite kernel in Ω . Assume that G satisfies the weak maximum principle (2.2). Fix $x \in \Omega$ and set $a = G1(x) \leq +\infty$. If a function $\phi: [0, a) \rightarrow [0, +\infty)$ satisfies the conditions of Lemma 2.1 and $\phi(t) = \phi(a)$ for $t \geq a$, then*

$$\int_0^{G1(x)} \phi(t) dt \leq G[\phi(bG1)](x) \quad \text{for all } x \in \Omega. \quad (2.8)$$

Proof. For any $y \in \Omega$, set

$$E_y = \{z \in \Omega: G1(z) \leq G1(y)\}.$$

Clearly,

$$G1_{E_y}(z) \leq G1(z) \leq G1(y) \quad \text{for all } z \in E_y.$$

Hence, by the weak maximum principle (2.3) applied to $f = 1_{E_y}$, we obtain

$$G1_{E_y}(z) \leq bG1(y) \quad \text{for all } z \in \Omega,$$

which implies, for $z = x$,

$$G1_{E_y}(x) \leq bG1(y). \quad (2.9)$$

Applying Lemma 2.1 to the σ -finite measure $\omega(dy) = G(x, dy)$ and the function $f = G1$, noticing that $\omega(E) = G1_E(x)$, and using (2.9), we obtain

$$\begin{aligned} \int_0^{G1(x)} \phi(t) dt &\leq \int_{\Omega} \phi(\omega\{z \in \Omega: G1(z) \leq G1(y)\}) \omega(dy) \\ &= \int_{\Omega} \phi(\omega(E_y)) \omega(dy) \\ &\leq \int_{\Omega} \phi(\mathfrak{b} G1(y)) \omega(dy) \\ &= G[\phi(\mathfrak{b} G1)](x), \end{aligned}$$

which proves (2.8). \square

Remark 2.6. In the particular case $\phi(t) = t^{r-1}$ ($t \geq 0$) where $r \geq 1$, Lemma 2.5 gives the following estimate:

$$[G1(x)]^r \leq r \mathfrak{b}^{r-1} G[(G1)^{r-1}](x) \quad \text{for all } x \in \Omega. \quad (2.10)$$

In the case $\phi(t) = t^{r-1}$ ($t > 0$) where $0 < r \leq 1$, it is easy to see that the converse inequality to (2.10) holds, that is,

$$[G1(x)]^r \geq r \mathfrak{b}^{r-1} G[(G1)^{r-1}](x) \quad \text{for all } x \in \Omega. \quad (2.11)$$

Lemma 2.7. In the setting of Lemma 2.5 define a sequence $\{f_k\}_{k=0}^{\infty}$ of functions on Ω by

$$f_0 = G1, \quad f_{k+1} = G(\phi(f_k)), \quad (2.12)$$

for all $k \geq 0$. Set

$$\psi(t) = \phi(\mathfrak{b}^{-1}t), \quad (2.13)$$

and define also the sequence $\{\psi_k\}_{k=0}^{\infty}$ of functions on $[0, \infty)$ by $\psi_0(t) = t$ and

$$\psi_{k+1}(t) = \int_0^t \psi \circ \psi_k(s) ds, \quad (2.14)$$

for all $k \geq 0$. Then, for all $x \in \Omega$ and $k \geq 0$,

$$\psi_k(f_0(x)) \leq f_k(x). \quad (2.15)$$

For example, we have

$$f_1 = G(\phi(f_0)), \quad f_2 = G(\phi(f_1)),$$

and

$$\psi_1(t) = \int_0^t \psi(s) ds, \quad \psi_2(t) = \int_0^t \psi(\psi_1(s)) ds.$$

Proof. For $k = 0$ estimate (2.15) is trivial. For $k = 1$ estimate (2.15) follows from Lemma 2.5 with ψ in place of ϕ , since by (2.8)

$$\psi_1(f_0(x)) = \int_0^{G1(x)} \psi(s)ds \leq G(\psi(\mathfrak{b}G1))(x) = G(\phi(G1))(x) = f_1(x).$$

Let us make an inductive step from k to $k + 1$, where $k \geq 1$. Fix $y \in \Omega$ and define the set

$$\Omega_y = \{z \in \Omega: f_k(z) \leq f_k(y)\}.$$

Then by (2.12) we have

$$G(1_{\Omega_y}\phi(f_{k-1}))(z) \leq f_k(z) \leq f_k(y) \quad \text{for all } z \in \Omega_y,$$

which implies by the weak maximum principle that

$$G(1_{\Omega_y}\phi(f_{k-1}))(x) \leq \mathfrak{b}f_k(y) \quad \text{for all } x \in \Omega. \quad (2.16)$$

Consider now the kernel

$$\hat{G}(x, dz) = G(x, 1_{\Omega_y}dz),$$

and define a sequence of functions $\{\hat{f}_k\}$ similarly to (2.12):

$$\hat{f}_0 = \hat{G}1 = G1_{\Omega_y}, \quad \hat{f}_{k+1} = \hat{G}(\phi(\hat{f}_k)) = G(1_{\Omega_y}\phi(\hat{f}_k)), \quad k \geq 0.$$

It follows from (2.16) that

$$\hat{f}_k(x) \leq \mathfrak{b}f_k(y) \quad \text{for all } x \in \Omega.$$

By the inductive hypothesis, we have, for all $x \in \Omega$,

$$\psi_k(\hat{f}_0(x)) \leq \hat{f}_k(x).$$

It follows that

$$\psi \circ \psi_k(\hat{f}_0(x)) \leq \psi(\hat{f}_k(x)) \leq \psi(\mathfrak{b}f_k(y)) = \phi(f_k(y)),$$

that is,

$$\psi \circ \psi_k(G1_{\Omega_y})(x) \leq \phi(f_k(y)) \quad \text{for all } x \in \Omega. \quad (2.17)$$

Fix now also $x \in \Omega$ and apply Lemma 2.1 with the σ -finite measure $\omega(dy) = G(x, dy)$. We obtain, using (2.14) and (2.17), that

$$\begin{aligned} \psi_{k+1}(f_0(x)) &= \int_0^{f_0(x)} \psi \circ \psi_k(s) ds = \int_0^{\omega(\Omega)} \psi \circ \psi_k(s) d\omega(s) \\ &\leq \int_{\Omega} \psi \circ \psi_k(\omega(z \in \Omega : f_k(z) \leq f(y))) \omega(dy) \\ &= \int_{\Omega} \psi \circ \psi_k(\omega(\Omega_y)) \omega(dy) \\ &= \int_{\Omega} \psi \circ \psi_k(G1_{\Omega_y}(x)) \omega(dy) \\ &\leq \int_{\Omega} \phi(f_k(y)) \omega(dy) \\ &= G(\phi(f_k))(x) = f_{k+1}(x), \end{aligned}$$

which finishes the inductive step. \square

Setting in Lemma 2.7 $\phi(t) = t^q$, $q > 0$, we obtain the following.

Corollary 2.8. *Under the hypotheses of Lemma 2.7, we have, for any $q > 0$, $k \geq 0$, and all $x \in \Omega$,*

$$[f_0(x)]^{1+q+\dots+q^k} \leq c(q, k) \mathfrak{b}^{q+q^2+\dots+q^k} f_k(x), \quad (2.18)$$

where f_k are defined by (2.12) with $\phi(t) = t^q$, and

$$c(q, k) = \prod_{j=1}^k (1 + q + \dots + q^j)^{q^{k-j}}. \quad (2.19)$$

In particular, in the case $q = 1$, for all $x \in \Omega$ we have

$$[f_0(x)]^{k+1} \leq (k+1)! \mathfrak{b}^k f_k(x). \quad (2.20)$$

Remark 2.9. A direct proof by induction using Lemma 2.5 gives a constant that grows in \mathfrak{b} much faster than $\mathfrak{b}^{q+q^2+\dots+q^k}$ in (2.18).

3. Monotone nonlinearities

In this section we will apply estimates of Section 2 to the following nonlinear problem. Let Ω and G be as above, that is (Ω, Ξ) is a measurable space and $G(x, dy)$ be a σ -finite kernel in Ω , satisfying the weak maximum principle (2.2).

Let $g: [1, +\infty) \rightarrow [0, +\infty)$ be a continuous, monotone non-decreasing function; set $g(+\infty) = \lim_{t \rightarrow +\infty} g(t)$. We consider the non-linear integral inequality

$$u(x) \geq G(g(u))(x) + 1 \text{ for all } x \in \Omega, \quad (3.1)$$

where $u: \Omega \rightarrow [1, \infty)$ is a measurable function. Our goal is to obtain sharp pointwise lower estimates of $u(x)$ which are better than the trivial estimate $u(x) \geq 1$. In what follows we always assume that $g(1) \geq 1$.

Remark 3.1. Indeed, if $g(1) = 0$, then simple examples, for instance, $g(t) = \log t$ and $u \equiv 1$, show that we cannot expect any non-trivial estimates for u . If $g(1) > 0$, then by renaming $\frac{g}{g(1)}$ back to g and changing G appropriately, we can assume that $g(1) = 1$. Hence, the assumption $g(1) \geq 1$ is natural in this setting.

The next theorem is our main result.

Theorem 3.2. *Let G be a σ -finite kernel on Ω satisfying the weak maximum principle (2.2) with $\mathfrak{b} \geq 1$. Let $g: [1, +\infty) \rightarrow [1, +\infty)$ be a continuous monotone non-decreasing function. Set*

$$F(t) = \int_1^t \frac{ds}{g(s)}, \quad t \geq 1. \quad (3.2)$$

If u satisfies (3.1) then, for all $x \in \Omega$ such that $u(x) < +\infty$, the following inequalities hold:

$$u(x) \geq 1 + \mathfrak{b} \left[F^{-1} \left(\mathfrak{b}^{-1} G1(x) \right) - 1 \right] \quad (3.3)$$

and

$$\mathfrak{b}^{-1} G1(x) < a := \int_1^{+\infty} \frac{ds}{g(s)}. \quad (3.4)$$

Note that the function F is defined on $[1, \infty)$. Hence, the inverse function F^{-1} is defined on $[0, a)$, and takes values in $[1, \infty)$. Hence, the condition (3.4) is necessary for the right-hand side of (3.3) to be well-defined.

Proof. Set for any $t \geq 0$

$$\phi(t) = g(t+1) \quad \text{and} \quad \psi(t) = \phi(\mathfrak{b}^{-1}t) = g(\mathfrak{b}^{-1}t+1). \quad (3.5)$$

Define the sequence $\{f_k\}$ of functions on Ω by (2.12), that is,

$$f_0 = G1, \quad f_{k+1} = G(\phi(f_k)).$$

We claim that, for all $k \geq 0$,

$$u \geq f_k + 1 \text{ in } \Omega. \quad (3.6)$$

Indeed, it follows from (3.1) that $u \geq 1$, and one more application of (3.1) yields

$$u \geq G(g(1)) + 1 \geq G1 + 1 = f_0 + 1,$$

that is, (3.6) for $k = 0$. If (3.6) is already proved for some $k \geq 0$, then substituting (3.6) into (3.1) yields

$$u \geq G(g(f_k + 1)) + 1 = G(\phi(f_k)) + 1 = f_{k+1} + 1,$$

which finishes the proof of (3.6).

Consider now the sequence $\{\psi_k\}_{k=0}^\infty$ of functions on $[0, \infty)$ defined by (2.14), that is, $\psi_0(t) = t$ and

$$\psi_{k+1}(t) = \int_0^t \psi \circ \psi_k(s) ds. \quad (3.7)$$

By Lemma 2.7, we have, for all $x \in \Omega$ and $k \geq 0$,

$$f_k(x) \geq \psi_k(f_0(x)),$$

which together with (3.6) imply

$$u(x) \geq \psi_k(G1(x)) + 1 \text{ for all } x \in \Omega.$$

By (3.5) the function ψ is monotone non-decreasing and $\psi \geq 1$, which implies that the sequence $\{\psi_k\}_{k=0}^\infty$ is non-decreasing, that is, $\psi_{k+1}(t) \geq \psi_k(t)$ for all $t \geq 0$. Indeed, for $k = 0$ it follows from

$$\psi_1(t) = \int_0^t \psi(t) dt \geq t = \psi_0(t),$$

and if $\psi_k \geq \psi_{k-1}$ is already proved then $\psi_{k+1} \geq \psi_k$ follows from (3.7) and the monotonicity of ψ .

Set

$$\psi_\infty(t) = \lim_{k \rightarrow \infty} \psi_k(t)$$

so that

$$u(x) \geq \psi_\infty(G1(x)) + 1 \text{ for all } x \in \Omega. \quad (3.8)$$

Let us fix $x \in \Omega$ such that $u(x) < +\infty$. It follows from (3.8) that

$$t_0 := G1(x) < +\infty \text{ and } \psi_\infty(t_0) < \infty.$$

Without loss of generality we may assume that $t_0 > 0$ since in the case $G1(x) = 0$ the estimates (3.3), (3.4) are obvious. Then we see that the function ψ_∞ is finite on $[0, t_0]$, positive on $(0, t_0]$ and satisfies the integral equation

$$\psi_\infty(t) = \int_0^t \psi \circ \psi_\infty(s) ds, \quad 0 < t \leq t_0. \quad (3.9)$$

It follows that ψ_∞ is continuously differentiable on $[0, t_0]$ and satisfies the differential equation

$$\frac{d\psi_\infty}{dt} = \psi(\psi_\infty(t)), \quad \psi_\infty(0) = 0. \quad (3.10)$$

Setting

$$\Psi(\xi) = \int_0^\xi \frac{ds}{\psi(s)} = \mathfrak{b} F(1 + \mathfrak{b}^{-1}\xi)$$

and observing that by (3.10)

$$\frac{d\Psi(\psi_\infty)(t)}{dt} = 1,$$

we obtain, for any $t \in [0, t_0]$,

$$\Psi(\psi_\infty(t)) = t. \quad (3.11)$$

It follows that, for $t = t_0$,

$$F(1 + \mathfrak{b}^{-1}\psi_\infty(t_0)) = \mathfrak{b}^{-1}t_0. \quad (3.12)$$

Since all values of F are located in $[0, a)$, we obtain that

$$\mathfrak{b}^{-1}t_0 < a,$$

which is equivalent to (3.4). Next, we obtain from (3.12) that

$$\psi_\infty(t_0) = \mathfrak{b}F^{-1}(\mathfrak{b}^{-1}t_0) - 1.$$

Substituting this into (3.8) yields (3.3), which finishes the proof. \square

Our methods are also applicable to non-linear integral inequalities of the type

$$u(x) + G(g(u)) \leq 1 \text{ in } \Omega, \quad (3.13)$$

defined on measurable functions $0 \leq u \leq 1$. Here $g: (0, 1] \rightarrow (0, +\infty)$ is a continuous, monotone non-increasing function and $g(0) = \lim_{t \rightarrow 0^+} g(t) \leq +\infty$.

We exclude the case $g(1) = 0$, since otherwise we cannot expect an upper estimate for u better than the trivial estimate $u \leq 1$. In fact, without loss of generality we may assume $g(1) \geq 1$ by using $\frac{g}{g(1)}$ and changing G appropriately as above (see Remark 3.1). Thus, we assume that $g: [0, 1] \rightarrow [1, +\infty]$.

Theorem 3.3. *Let G be a σ -finite kernel on Ω satisfying the weak maximum principle (2.2) with $\mathfrak{b} \geq 1$. Let $g: [0, 1] \rightarrow [1, +\infty]$ be a continuous monotone non-increasing function. Set*

$$F(t) = \int_t^1 \frac{ds}{g(s)}, \quad 0 \leq t \leq 1. \quad (3.14)$$

If $u \geq 0$ satisfies (3.13) then, for all $x \in \Omega$ such that $u(x) > 0$, the following inequalities hold:

$$u(x) \leq 1 - \mathfrak{b} \left[1 - F^{-1}(\mathfrak{b}^{-1}G1(x)) \right], \quad (3.15)$$

and

$$\mathfrak{b}^{-1} G1(x) < F(1 - \mathfrak{b}^{-1}) = \int_{1-\mathfrak{b}^{-1}}^1 \frac{ds}{g(s)}, \quad (3.16)$$

so that the right-hand side of (3.15) is well-defined and positive.

Proof. For any $t \in [0, 1]$ set

$$\phi(t) = g(1 - t) \quad \text{and} \quad \psi(t) = \phi(\mathfrak{b}^{-1}t) = g(1 - \mathfrak{b}^{-1}t), \quad (3.17)$$

so that ϕ and ψ are non-decreasing. As in the proof of Theorem 3.2, define the sequence $\{f_k\}_{k=0}^\infty$ of functions on Ω by (2.12),

$$f_0 = G1, \quad f_{k+1} = G(\phi(f_k)).$$

We claim that $0 \leq f_k \leq 1$ for all $k \geq 0$, so that $\phi(f_k)$ is well-defined, and moreover

$$u \leq 1 - f_k \quad \text{in } \Omega. \quad (3.18)$$

Indeed, obviously $u \leq 1$, and hence $g(u) \geq g(1) \geq 1$. Consequently by (3.13),

$$u \leq 1 - G(g(1)) \leq 1 - G1 = 1 - f_0,$$

so that $f_0 \leq 1$, and (3.18) holds for $k = 0$. If (3.18) has been proved for some $k \geq 0$, then substituting (3.18) into (3.13) yields

$$u \leq 1 - G(g(1 - f_k)) = 1 - G(\phi(f_k)) = 1 - f_{k+1},$$

which proves (3.18). In particular, $0 \leq f_k \leq 1$ for all $k \geq 0$.

Set $t_0 := G1(x) = f_0(x) \in [0, 1]$. Consider now the sequence $\{\psi_k\}_{k=0}^\infty$ of functions on $[0, t_0]$ defined by (2.14),

$$\psi_0(t) = t, \quad \psi_{k+1}(t) = \int_0^t \psi \circ \psi_k(s) ds.$$

We need to show that the functions $\psi_k(t)$ are well-defined, that is, $\psi_k(t) \in [0, 1]$ for all $t \in [0, t_0]$ and $k \geq 1$, and

$$f_k(x) \geq \psi_k(f_0(x)). \quad (3.19)$$

By (3.18), we deduce

$$G(g(u)) \geq G(g(1 - f_k)) = G(\phi(f_k)) = f_{k+1}. \quad (3.20)$$

Clearly, ψ_1 is well-defined. Hence, by Lemma 2.7 and the preceding inequality with $k = 0$,

$$1 \geq 1 - u(x) \geq G(g(u))(x) \geq f_1(x) \geq \psi_1(f_0(x)) = \psi_1(t_0).$$

Since ψ_1 is non-decreasing, we see that $\psi_1(t) \in [0, 1]$ for all $t \in [0, t_0]$.

If the inequalities $\psi_k(t_0) \leq 1$ and (3.19) have been proved for some $k \geq 1$, then $\psi_{k+1}(t)$ is well-defined on $[0, t_0]$. By Lemma 2.7 and (3.20),

$$1 \geq 1 - u(x) \geq G(g(u))(x) \geq f_{k+1}(x) \geq \psi_{k+1}(f_0(x)) = \psi_{k+1}(t_0).$$

Since $\psi_{k+1}(t)$ is a non-decreasing function, it follows that $\psi_{k+1}(t) \leq 1$ for all $t \in [0, t_0]$, and (3.19) holds for all $k \geq 1$. Consequently, for all $k \geq 0$,

$$1 \geq u(x) + f_k(x) \geq u(x) + \psi_k(f_0(x)). \quad (3.21)$$

The rest of the proof is similar to that of Theorem 3.2. Passing to the limit as $k \rightarrow \infty$ in (3.21) yields

$$1 \geq u(x) + \psi_\infty(f_0(x)),$$

where $\psi_\infty(t)$ is the unique solution of the integral equation (3.9) in the interval $0 \leq t \leq t_0$. From this we deduce that

$$\Psi(\psi_\infty(t)) = t, \quad 0 \leq t \leq t_0,$$

where, for $\xi \in [0, 1]$,

$$\Psi(\xi) = \int_0^\xi \frac{ds}{\psi(s)} = \mathfrak{b} F(1 - \mathfrak{b}^{-1}\xi).$$

Here F is defined by (3.14). Hence,

$$\psi_\infty(t) = \Psi^{-1}(t) = \mathfrak{b} (1 - F^{-1}(\mathfrak{b}^{-1}t)), \quad 0 \leq t \leq t_0, \quad t_0 \in \text{Range}(\Psi).$$

Thus,

$$G1(x) = t_0 \leq \int_0^1 \frac{dt}{\psi(t)} = \mathfrak{b} \int_{1-\mathfrak{b}^{-1}}^1 \frac{dt}{g(t)},$$

so that (3.15) holds, where its right-hand side is well defined. Clearly, (3.15) implies (3.16) provided $u(x) > 0$. \square

We now consider some special cases of the integral inequalities (3.1) and (3.13). Let $g(t) = t^q$ ($q > 0$) in the case of (3.1), that is,

$$u \geq G(u^q) + 1 \quad \text{in } \Omega. \quad (3.22)$$

Corollary 3.4. *Let $q > 0$. Under the assumptions of Theorem 3.2, suppose that u satisfies (3.22).*

If $q \neq 1$, then

$$u(x) \geq 1 + \mathfrak{b} \left[\left(1 + (1 - q)\mathfrak{b}^{-1}G1(x) \right)^{\frac{1}{1-q}} - 1 \right], \quad (3.23)$$

where in the case $q > 1$, for all $x \in \Omega$ such that $u(x) < +\infty$,

$$\mathfrak{b}^{-1}G1(x) < \frac{1}{q-1}. \quad (3.24)$$

In the case $q = 1$,

$$u(x) \geq 1 + \mathfrak{b} \left(e^{\mathfrak{b}^{-1}G1(x)} - 1 \right), \quad x \in \Omega. \quad (3.25)$$

Proof. We apply Theorem 3.2 with $g(t) = t^q$, $t \geq 1$. If $q > 0$ ($q \neq 1$), we have

$$F(t) = \int_1^t s^{-q} ds = \frac{1}{1-q} (t^{1-q} - 1), \quad t \geq 1,$$

and consequently

$$F^{-1}(\tau) = [1 + (1-q)\tau]^{\frac{1}{1-q}}, \quad 0 \leq \tau \leq \frac{1}{q-1} \text{ if } q > 1; \quad \tau \geq 0 \text{ if } 0 < q < 1.$$

Therefore, for all $x \in \Omega$ such that $u(x) < +\infty$, we deduce (3.23), where $G1(x) < \frac{\mathfrak{b}}{1-q}$, so that the right-hand side of (3.23) is well defined, that is, (3.24) holds.

In the case $q = 1$, we have $F(t) = \log t$ for $t \geq 1$, and $F^{-1}(\tau) = e^\tau$ for $\tau \geq 0$, which gives (3.25). \square

We now consider inequalities of the type (3.13) with $g(t) = t^q$ for $q < 0$, that is,

$$u + G(u^q) \leq 1 \quad \text{in } \Omega. \quad (3.26)$$

Corollary 3.5. *Let $q < 0$. Under the assumptions of Theorem 3.3, suppose that $u \geq 0$ satisfies (3.26). Then, for all $x \in \Omega$ such that $u(x) > 0$,*

$$G1(x) < \frac{\mathfrak{b}}{1-q} \left[1 - (1 - \mathfrak{b}^{-1})^{1-q} \right], \quad (3.27)$$

and

$$u(x) \leq 1 - \mathfrak{b} \left[1 - \left(1 - (1-q)\mathfrak{b}^{-1}G1(x) \right)^{\frac{1}{1-q}} \right]. \quad (3.28)$$

Proof. We apply Theorem 3.3 with $g(t) = t^q$, $q < 0$, where $t \in (0, 1]$. In this case,

$$F(t) = \int_t^1 s^{-q} ds = \frac{1}{1-q} (1 - t^{1-q}), \quad 0 \leq t \leq 1.$$

Then

$$F^{-1}(\tau) = [1 - (1-q)\tau]^{\frac{1}{1-q}}, \quad 0 \leq \tau \leq \frac{1}{1-q}.$$

Therefore, for all $x \in \Omega$ such that $u(x) > 0$, we deduce (3.28), where $G1(x) \leq \frac{\mathfrak{b}}{1-q}$ so that the right-hand side of (3.28) is well defined. Moreover, (3.27) holds since $u(x) > 0$ in (3.28). \square

In the following corollary we give pointwise estimates for super-solutions to homogeneous equations in the sublinear case.

Corollary 3.6. *Let G be a σ -finite kernel on Ω satisfying the weak maximum principle (2.2) with $\mathfrak{b} \geq 1$. Let $0 < q < 1$. If $u > 0$ in Ω satisfies*

$$u \geq G(u^q) \quad \text{in } \Omega, \quad (3.29)$$

then

$$u(x) \geq (1 - q)^{\frac{1}{1-q}} \mathfrak{b}^{-\frac{q}{1-q}} (G1(x))^{\frac{1}{1-q}}, \quad x \in \Omega. \quad (3.30)$$

Remark 3.7. The constant $(1 - q)^{\frac{1}{1-q}}$ in (3.30) coincides with that in [13, Theorem 3.3], if $\mathfrak{b} = 1$, and is sharp.

Proof. For $a > 0$, set

$$E_a = \{y \in \Omega: u(y) \geq a\}.$$

Then

$$u \geq G(u^q) \geq a^q (G1_{E_a} u^q) \quad \text{in } E_a.$$

Iterating this inequality, we obtain

$$u \geq a^{q^{k+1}} Gf_k \quad \text{in } E_a,$$

where f_k is defined by (2.12) with $\phi(t) = t^q$. Hence, by Corollary 2.8,

$$u \geq c(q, k)^{-1} a^{q^{k+1}} \mathfrak{b}^{-q(1+q+\dots+q^{k-1})} (G1_{E_a}(x))^{1+q+\dots+q^k} \quad \text{in } E_a.$$

Notice that

$$\begin{aligned} c(q, k) &= \prod_{j=1}^k (1 + q + \dots + q^j)^{q^{k-j}} \\ &< \prod_{j=1}^k (1 - q)^{-q^{k-j}} \\ &< (1 - q)^{-(1-q)^{-1}}. \end{aligned}$$

It follows

$$u \geq (1 - q)^{(1-q)^{-1}} a^{q^{k+1}} \mathfrak{b}^{-q(1+q+\dots+q^{k-1})} (G1_{E_a}(x))^{1+q+\dots+q^k} \quad \text{in } E_a.$$

Letting $k \rightarrow +\infty$, we obtain

$$u \geq (1 - q)^{\frac{1}{1-q}} \mathfrak{b}^{-\frac{q}{1-q}} (G1_{E_a})^{\frac{1}{1-q}} \quad \text{in } E_a.$$

Finally, letting $a \rightarrow 0^+$ yields (3.30) in Ω . □

4. Quasi-metric kernels

Consider the setting of Example 2.3, that is, Ω is a locally compact Hausdorff space with countable base, ω is a Radon measure on Ω . Let $K : \Omega \times \Omega \rightarrow (0, +\infty]$ be a lower semi-continuous function. Assume that for any $x \in \Omega$, $K(x, \cdot) \in L^1_{\text{loc}}(\Omega, \omega)$. Set

$$Gf(x) = \int_{\Omega} K(x, y) f(y) d\omega(y).$$

The kernel K is called *quasi-metric* (see [8, 14, 16]) if K is symmetric, that is, $K(x, y) = K(y, x)$ and $d(x, y) = \frac{1}{K(x, y)}$ is quasi-metric, that is, there exists a *quasi-metric constant* $\varkappa > 0$ such that the quasi-triangle inequality holds:

$$d(x, y) \leq \varkappa [d(x, z) + d(y, z)], \quad \forall x, y, z \in \Omega.$$

Without loss of generality we may assume that $d(x, y) \neq 0$ for some $x, y \in \Omega$, so that $\varkappa \geq \frac{1}{2}$.

The following lemma is proved in [22, Lemma 3.5].

Lemma 4.1. *Suppose G is a quasi-metric kernel in Ω with quasi-metric constant \varkappa . Then G satisfies the weak maximum principle (1.8) with constant $\mathfrak{b} = 2\varkappa$.*

In the next lemma we consider a certain modification of a quasi-metric kernel.

Lemma 4.2. *Suppose K is a quasi-metric kernel in Ω with constant \varkappa . For $w \in \Omega$, let $\Omega_w = \{x \in \Omega : K(x, w) < +\infty\}$. Then*

$$K_w(x, y) = \frac{K(x, y)}{K(x, w) K(y, w)}, \quad x, y \in \Omega_w, \quad (4.1)$$

is a quasi-metric kernel on Ω_w with quasi-metric constant $4\varkappa^2$.

In particular, K_w satisfies the weak maximum principle (1.8) in Ω_w with constant $\mathfrak{b} = 8\varkappa^3$.

Proof. This is immediate from the so-called Ptolemy inequality for quasi-metric spaces, [8, Lemma 2.2] (see also [15, Proposition 8.1]),

$$d(x, y) d(z, w) \leq 4\varkappa^2 [d(x, w) d(y, z) + d(x, z) d(y, w)], \quad \forall x, y, z, w \in \Omega. \quad (4.2)$$

Dividing both sides of the preceding inequality by $d(x, w) d(y, w) d(z, w)$, we deduce

$$\frac{d(x, y)}{d(x, w) d(y, w)} \leq 4\varkappa^2 \left[\frac{d(x, z)}{d(x, w) d(z, w)} + \frac{d(y, z)}{d(y, w) d(z, w)} \right],$$

for all $x, y, z \in \Omega_w$. □

Let $h : \Omega \rightarrow (0, +\infty)$ be a lower semicontinuous function on Ω . For a general kernel $K : \Omega \times \Omega \rightarrow (0, +\infty]$, consider a modified kernel

$$K^h(x, y) = \frac{K(x, y)}{h(x)h(y)} \quad \text{for } x, y \in \Omega. \quad (4.3)$$

Here we discuss the question how to verify the weak maximum principle for K^h .

Remark 4.3. As we will demonstrate below (see Lemma 4.5), K^h satisfies the weak maximum principle (1.8) provided K satisfies the following form of the *weak domination principle*:

Given a positive lower semicontinuous function h in Ω ,

$$K\mu(x) \leq Mh(x) \quad \forall x \in \text{supp}(\mu) \implies K\mu(x) \leq \mathfrak{b}Mh(x) \quad \forall x \in \Omega, \quad (4.4)$$

for any compactly supported Radon measure μ with finite energy in Ω , i.e., $\int_{\Omega} K\mu d\mu < +\infty$, and any constant $M > 0$.

This property is sometimes called a *dilated domination principle* (see, e.g., [17]). In the case where (4.4) holds with $\mathfrak{b} = 1$ for any $h = K\nu + a$, where ν is a Radon measure and $a \geq 0$ is a constant, it is called the *complete maximum principle* (see e.g., [2, 14]).

The weak domination principle holds for Green's kernels associated with a large class of local and non-local operators, and super-harmonic h .

Remark 4.4. It is easy to see that, for a quasi-metric kernel K , the modified kernel K^h with $h = K\nu > 0$, where ν is a Radon measure, is generally not quasi-metric. However, it does satisfy the weak maximum principle (1.8) under some mild assumptions. See Lemma 4.6 below.

The modified kernel K^h in this case is essentially quasi-metric if ν is a measure supported at a single point $w \in \Omega$, i.e., when $h(x) = cK(x, w)$, $c > 0$, by Lemma 4.2.

Let us denote by $M^+(\Omega)$ the class of Radon measures in Ω .

Lemma 4.5. Suppose K is a non-negative lower semicontinuous kernel in Ω which satisfies the domination principle (4.4). Suppose h is a positive lower semicontinuous function in Ω . Then the modified kernel K^h defined by (4.3) satisfies the weak maximum principle (1.8) in $\Omega' = \Omega \setminus \{x : h(x) < +\infty\}$ with the same constant \mathfrak{b} .

In particular, if (4.4) holds for K and h with $\mathfrak{b} = 1$, then K^h satisfies the strong maximum principle in Ω' .

Proof. For $\nu \in M^+(\Omega')$ with compact support, let $d\tilde{\nu} = \frac{1}{h(x)}d\nu$. Notice that h is bounded below by a positive constant on any compact set so that $\tilde{\nu} \in M^+(\Omega)$, and $\text{supp}(\tilde{\nu}) \subseteq \text{supp}(\nu)$.

Let

$$\Omega_m := \{x \in \Omega : h(x) \leq m\}, \quad m = 1, 2, \dots \quad (4.5)$$

Clearly, each Ω_m is a closed set, and $\Omega' = \bigcup_{m=1}^{+\infty} \Omega_m$. Let $d\nu_m = \chi_{\Omega_m}d\nu$, so that $\text{supp}(\nu_m) \subseteq \Omega_m$.

Suppose that, for a positive constant M ,

$$K^h v(x) \leq M \text{ for all } x \in \text{supp}(v).$$

Then obviously

$$K^h v_m(x) \leq M \text{ for all } x \in \text{supp}(v_m).$$

It follows that

$$K \tilde{v}_m(x) \leq M h(x) \text{ for all } x \in \text{supp}(\tilde{v}_m), \quad \text{where} \quad d\tilde{v}_m(x) = \frac{1}{h(x)} dv_m.$$

Clearly, \tilde{v}_m has finite energy with respect to K , since

$$\int_{\Omega} K \tilde{v}_m d\tilde{v}_m \leq M \int_{\Omega} h d\tilde{v}_m = M \int_{\Omega} dv_m < +\infty.$$

Hence, by (4.4)

$$K \tilde{v}_m(x) \leq \mathfrak{b} M h(x) \quad \forall x \in \Omega.$$

Consequently, by the monotone convergence theorem

$$K \tilde{v}(x) \leq \mathfrak{b} M h(x) \quad \forall x \in \Omega'.$$

Equivalently,

$$K^h v(x) \leq \mathfrak{b} M \quad \forall x \in \Omega'.$$

Thus, K^h satisfies the weak maximum principle (respectively, the strong maximum principle if $\mathfrak{b} = 1$) in Ω' . \square

Lemma 4.6. *Let K be a quasi-metric kernel on $\Omega \times \Omega$, continuous in the extended sense. Let $h = Kv$ where $v \in M^+(\Omega)$, $h \not\equiv +\infty$. Then the modified kernel K^h defined by (4.3) satisfies the weak maximum principle in $\Omega' = \{x \in \Omega : h(x) < +\infty\}$.*

Proof. If $v = \delta_w$ for some $w \in \Omega$ then by Lemma 4.2 the modified kernel K_w given by (4.1) is a quasi-metric kernel on $\Omega_w = \{x \in \Omega : K(x, w) < +\infty\}$. By Lemma 4.1, K_w satisfies the weak maximum principle with constant $\mathfrak{b} = 8\kappa^3$ in $\Omega' = \Omega_w$.

To show that, for general $h = Kv$, the modified kernel K^h defined by (4.3) satisfies the weak maximum principle in Ω' , we invoke the idea used in [20, Theorem 7], (see also [17, 18]) which reduces it to the *elementary domination principle* in the case $v = \delta_w$.

Suppose first that $\mu \in M^+(\Omega)$ is a measure with compact support and of finite energy, and $h = Kv$. Let us show that K satisfies (4.4) for $\mu \in M^+(\Omega)$. To this end, we argue by contradiction. Assume that

$$K\mu \leq Kv \quad \text{on } F = \text{supp}(\mu), \tag{4.6}$$

but there exists $w \in \Omega \setminus F$ such that

$$K\mu(w) > \mathfrak{b} K\nu(w), \quad (4.7)$$

where without loss of generality we may let $K\nu(w) < +\infty$.

Notice that quasi-metric kernels are symmetric, and strictly positive. Hence, $\text{cap}(F) < +\infty$ for any compact set $F \subset \Omega$ (see [9]), and there exists an extremal measure $\mu_F \in M^+(\Omega)$ of finite energy, with $\text{supp}(\mu_F) \subseteq F$, such that by [20, Lemma 1*], (see also [17, 18]),

$$K\mu_F(z) \leq K(z, w), \quad \forall z \in \text{supp}(\mu_F), \quad (4.8)$$

and

$$K\mu_F(z) \geq K(z, w) \quad \text{on } F. \quad (4.9)$$

Since K_w is a quasi-metric kernel in Ω_w , it satisfies the weak maximum principle with constant $\mathfrak{b} = 8\kappa^3$, and consequently G satisfies the domination principle (4.4) with $\nu = \delta_w$ and the same constant \mathfrak{b} in Ω_w . In fact, the domination principle for μ_F and $\nu = \delta_w$ holds in Ω , *i.e.*,

$$K\mu_F(x) \leq \mathfrak{b} K(x, w), \quad \forall x \in \Omega, \quad (4.10)$$

where $\mathfrak{b} = 8\kappa^3$, since the right-hand side of (4.10) is infinite on $\Omega \setminus \Omega_w$, and for all measures of finite energy $\mu(\Omega \setminus \Omega_w) = 0$. Indeed, by the quasi-triangle inequality $K(x, y) = \frac{1}{d(x, y)} = +\infty$ if $x, y \in \Omega \setminus \Omega_w$, and so $K\mu = +\infty$ on $\Omega \setminus \Omega_w$, unless $\mu(\Omega \setminus \Omega_w) = 0$.

We denote by $\mathcal{E}(\mu, \nu)$ the mutual energy of the measures $\mu, \nu \in M^+(\Omega)$:

$$\mathcal{E}(\mu, \nu) := \int_{\Omega} K\nu d\mu = \int_{\Omega} K\mu d\nu. \quad (4.11)$$

Let us estimate the mutual energy $\mathcal{E}(\mu_F, \nu)$. Integrating both sides of (4.10) against $d\nu$ we deduce

$$\begin{aligned} \mathcal{E}(\mu_F, \nu) &= \int_{\Omega} K\mu_F d\nu \\ &\leq \mathfrak{b} \int_{\Omega} K(x, w) d\nu(x) = \mathfrak{b} G\nu(w). \end{aligned}$$

On the other hand, it follows from (4.9) and (4.7) that

$$\begin{aligned} \mathcal{E}(\mu_F, \mu) &= \int_F K\mu_F d\mu \\ &\geq \int_F K(x, w) d\mu(x) \\ &= K\mu(w) > \mathfrak{b} K\nu(w). \end{aligned}$$

Since $\mathcal{E}(\mu_F, \nu) \geq \mathcal{E}(\mu_F, \mu)$ by (4.6), we arrive at a contradiction.

Suppose now that $\mu \in M^+(\Omega)$ has compact support $F \subset \Omega'$, and $h = Kv$. Then for $\Omega_m \subset \Omega'$ defined by (4.5) and $d\mu_m = \chi_{\Omega_m} d\mu$ we have

$$K\mu_m \leq h \leq m \quad \text{in } \Omega_m.$$

Consequently, $\mu_m \in M^+(\Omega)$ has finite energy, $\text{supp}(\mu_m) \subset F \cap \Omega_m$ is a compact set, and by the previous case

$$K\mu_m(x) \leq \mathfrak{b} h(x), \quad x \in \Omega',$$

for m large enough. Passing to the limit as $m \rightarrow +\infty$ we obtain by the monotone convergence theorem

$$K\mu(x) \leq \mathfrak{b} h(x), \quad x \in \Omega'. \quad \square$$

5. The weak domination principle and nonlinear integral inequalities

In the setting of Example 2.2, let Ω be a locally compact Hausdorff space with countable base, and let $G(x, dy)$ be a Radon kernel in Ω . Let $h : \Omega \rightarrow (0, +\infty)$ be a given positive lower semi-continuous function in Ω . In particular, $\inf_F h > 0$ for every compact set $F \subset \Omega$.

In this section we consider super-solutions $u : \Omega \rightarrow [0, +\infty)$ of

$$u(x) \geq G(u^q)(x) + h(x) \text{ in } \Omega, \quad (5.1)$$

in the case $q > 0$, and sub-solutions $u : \Omega \rightarrow (0, +\infty)$ of

$$u(x) \leq -G(u^q)(x) + h(x) \text{ in } \Omega, \quad (5.2)$$

in the case $q < 0$.

We will assume that G satisfies the *weak domination principle* in the following form:

For any bounded measurable function $f \geq 0$ with compact support,

$$Gf(x) \leq h(x) \text{ in } \text{supp}(f) \implies Gf(x) \leq \mathfrak{b} h(x) \text{ in } \Omega, \quad (5.3)$$

provided Gf is bounded on $\text{supp}(f)$.

Our main result in this setup is as follows.

Theorem 5.1. *In the above setting, for a given function h , assume that G satisfies the weak domination principle (5.3) in Ω . Suppose that $u \geq 0$ satisfies (5.1) if $q > 0$, or $u > 0$ and satisfies (5.2) if $q < 0$. Then $u(x)$ satisfies the following estimates for all $x \in \Omega$:*

(i) If $q > 0, q \neq 1$, then

$$u(x) \geq h(x) \left\{ 1 + \mathfrak{b} \left[\left(1 + \frac{(1-q) G(h^q)(x)}{\mathfrak{b} h(x)} \right)^{\frac{1}{1-q}} - 1 \right] \right\}, \quad (5.4)$$

where in the case $q > 1$ necessarily

$$G(h^q)(x) < \frac{\mathfrak{b}}{q-1} h(x). \quad (5.5)$$

(ii) If $q = 1$, then

$$u(x) \geq h(x) \left[1 + \mathfrak{b} \left(e^{\mathfrak{b}^{-1} \frac{G(h)(x)}{h(x)}} - 1 \right) \right]. \quad (5.6)$$

(iii) If $q < 0$, then

$$u(x) \leq h(x) \left\{ 1 - \mathfrak{b} \left[1 - \left(1 - \frac{(1-q) G(h^q)(x)}{\mathfrak{b} h(x)} \right)^{\frac{1}{1-q}} \right] \right\} \quad (5.7)$$

and necessarily

$$G(h^q)(x) < \frac{\mathfrak{b}}{1-q} \left[1 - (1 - \mathfrak{b}^{-1})^{1-q} \right] h(x). \quad (5.8)$$

Proof. Suppose first that $q > 0$. Let us consider a modified kernel

$$G^h(x, dy) = \frac{h(y)^q}{h(x)} G(x, dy).$$

Clearly, G^h is also a Radon kernel on any subset

$$\Omega_m = \{x \in \Omega : h(x) \leq m\}, \quad m \geq 1. \quad (5.9)$$

Notice that each Ω_m is closed, $\Omega_m \subseteq \Omega_{m+1}$, and $\bigcup_{m=1}^{\infty} \Omega_m = \Omega$.

Setting $G_m^h = G^h(x, 1_{\Omega_m} dy)$ and

$$v(x) := \frac{u(x)}{h(x)}, \quad x \in \Omega, \quad (5.10)$$

we see that v satisfies the inequality

$$v(x) \geq G_m^h(v^q)(x) + 1 \quad \text{for all } x \in \Omega. \quad (5.11)$$

Moreover, G_m^h satisfies the weak maximum principle (2.4) in Ω with the same constant \mathfrak{b} , that is, for any bounded measurable function f with compact support in Ω ,

$$\frac{1}{h} G(1_{\Omega_m} h^q f) \leq 1 \text{ in } \text{supp}(f) \implies \frac{1}{h} G(1_{\Omega_m} h^q f) \leq \mathfrak{b} \text{ in } \Omega. \quad (5.12)$$

Indeed, this follows from the weak domination principle (5.3) applied to $1_{\Omega_m} h^q f$ in place of f , which yields

$$G(1_{\Omega_m} h^q f) \leq h \text{ in } \text{supp}(f) \cap \Omega_m \implies G(1_{\Omega_m} h^q f) \leq \mathfrak{b} h \text{ in } \Omega. \quad (5.13)$$

This proves (5.12).

Hence, by Corollary 3.4 with G_m^h in place of G , it follows from (5.11) that v satisfies the following estimates for all $x \in \Omega$:

$$v(x) \geq 1 + \mathfrak{b} \left[\left(1 + \mathfrak{b}^{-1}(1-q) G_m^h(1)(x) \right)^{\frac{1}{1-q}} - 1 \right], \quad (5.14)$$

if $q > 0, q \neq 1$, where in the case $q > 1$, we have

$$G_m^h(1)(x) < \frac{\mathfrak{b}}{q-1}. \quad (5.15)$$

If $q = 1$, then

$$v(x) \geq 1 + \mathfrak{b} \left(e^{\mathfrak{b}^{-1} G_m^h(1)(x)} - 1 \right). \quad (5.16)$$

Passing to the limit as $m \rightarrow \infty$ we deduce by the monotone convergence theorem that, for $q > 0, q \neq 1$,

$$v(x) \geq 1 + \mathfrak{b} \left[\left(1 + \mathfrak{b}^{-1}(1-q) G^h(1)(x) \right)^{\frac{1}{1-q}} - 1 \right],$$

where the strict inequality holds for $q > 1$ in

$$G^h(1)(x) < \frac{\mathfrak{b}}{q-1},$$

since in the preceding estimate we have $v(x) = u(x) h(x) < +\infty$. If $q = 1$, then

$$v(x) \geq 1 + \mathfrak{b} \left(e^{\mathfrak{b}^{-1} G^h(1)(x)} - 1 \right).$$

Going back from v, G^h to u, G in these estimates yields that (5.4) or (5.6) hold at every $x \in \Omega$, and in the case $q > 1$ the necessary condition (5.5) holds.

In the case $q < 0$, estimates (5.7) and (5.8) are deduced in a similar way from Corollary 3.5, provided $u(x) > 0$. \square

Remark 5.2. The results of Section 4 show that, in that setup, the estimates of Theorem 5.1 hold for quasi-metric kernels K and $h = K\nu$ in $\Omega' = \{x \in \Omega : h(x) < +\infty\}$, for all Radon measures ν in Ω such that $K\nu \not\equiv +\infty$.

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